

## TAVOLI

A schematic diagram of a four-bar linkage mechanism. It consists of four rigid links connected by revolute joints. Link 1 is the fixed frame, represented by two ground symbols. Link 2 is the crank, labeled 'A', which is connected to the frame at point 'B' and to Link 3 at point 'C'. Link 3 is the coupler link, labeled 'D', which is connected to Link 2 at point 'C' and to Link 4 at point 'D'. Link 4 is the follower link, labeled 'B', which is connected to Link 3 at point 'D' and to the frame at point 'A'. Arrows indicate the direction of motion: Link 2 rotates counter-clockwise, and Link 4 rotates clockwise.